Specifications

Input Outputs: Electromechanical relay SSR MOS gate Output for external SSR - REL1 - RFI 2 Serial Interface

Power Supply

Auxiliary Supply Output Consumption Measurement Error Temperature Drift RTD Line Error Cold-junction Error Operating Temperature / Humidity Protection Class: front / terminals

Warranty and Support

serial number

manufacturing date

QC check mark(passed) (stamp)

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Wiring

grounding the device

is mandatory for covering

through terminal 2

safety standards.

QD-8.2.4-WC

Warrantv BASI Instrument AB warrants this product e from defects in materials and workmanship for 2 years. If your unit is found to be defective within that time, we will promptly repair or replace it. This warranty does not cover accidental damage, wear or tear, or consequential or incidental loss. This warranty does not cover any defects caused by wrong transportation, storage, installation, or operating (see 'Specifications').

Technical support

In the unlikely event that you encounter a problem with your BASI device, please call your local dealer or contact directly our support team.

to be	fre

programmable

1A/250VAC

□ 230 VAC,

less than 3 VA

IP54 / IP20

 $\leq \pm 0.3\%$ from span

 \leq 0.02% from span for 1 °C

 $\leq \pm$ 0.001%/ Ω at $R_{lin} \leq 50~\Omega$

-10...65 °C / 0...85% RH

 $\leq \pm$ 1 °C at air temperature -10...80 °C

□ 24 VDC.

5...24 VDC, 30 mA

□ RS485, isolated,

5A/250VAC with NO/NC contact

BRS485 for "PolyMonitor", isolated

 \Box relay, \Box SSR, \Box MOS gate, \Box for ext. SSR \Box relay, \Box SSR, \Box MOS gate, \Box for ext. SSR

 $\Box \leq U_p$ (DC); $\leq 1.2^*U_p$ (AC), $\Box 24$ VDC, 30 mA

□ 90...250 VAC/DC,

□ 12...24 VAC/DC.

0.1A/60V, optically isolated

up to 2

		Table
Parameter	Symbol	Value
Input Type	inp	<pre>pt100,pt1000, ptc1,ptc2, r.0.1k, t.c.b,t.c.j, t.c.k,t.c.r, t.c.s,t.c.t, u,u.0.10, i.0.20,i.4.20</pre>
Unit	unit	c,f
Point Position	pnt	0,1,2
Input Low	i.hi	-19999999
Input High	i.lo	-19999999
Input Correction	i.cor	-19999999
Address	addr	1254
Baud Rate	baud	1200,2400, 4800,9600
Gradient	grad	09999
Filter Time	f.t	09999
Filter Band	f.b	0M
Input Value	p.v	*
Error Info	error	**

out Value (read-only)

numerical value with ISU - measured input value sat.lo - ADC under-range sat.hi - ADC over-range

inp.br - sensor break break - device failure

noise - noisy measurement

** Error Info

- 0 initializes non-volatile memory -1 - error FR, L (read-only)
- 1...29 errors Er. [] 1... Er. 29 (read-only)

col

Protocol architecture

The protocol is based ٠ on UART protocol with: Baud Rate - as defined

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- by parameter Baud Rate;
- Data bits 8; Parity Control - Even;
- Stop bit 1. ASCII protocol is used
- for communicating, and the information is exchanged in frames.
- Each frame consists of 1, or 2 words separated by byte 32 (SPACE), and ends with bytes 13 (CR) and 10 (LF). The first word in the frame denotes a parameter 'Symbol' as taken from Table 2 and the second word (if needed) is the parameter 'Value', both spelled with only small Latin letters, digits, dots, and/or the '-' sign.

Device activating

- To respond to commands, the device should be active.
- For a device to be activated, it must receive a Ux command, where 'x' is the value of the parameter Address or the value '255' (if device address is unknown), and respond to it with ok.
- If a device does not respond even to U255, check the UART protocol settings, chiefly Baud Rate value.

$\begin{array}{c} 2-\text{wire} \\ \text{transmitter} \\ \hline \mathbf{U} \\ \mathbf{H} \\$	Input signal Connect the i with regard to through the re on the device 3-wire voltag be supplied e
$\begin{array}{c c} SSR1 & \bullet \\ extern. & \bullet \\ SSR2 & \bullet \\ extern. & \bullet \\ MOS1 & SSR1 & \bullet \\ \hline extern. & \bullet \\ MOS2 & SSR2 & \bullet \\ \hline extern. & \bullet \\ \end{array}$	Output wirin Connect the with regard to (see 'Specifi via the respe
B 0 10 A 0 11 GND 0 12	RS485 wirin Connect the to RS485 net via the respe
 Important notes: Strictly observe the requirements for RS485 network building! With DC power supply, the polarity does not matter. In case of 90250 VAC/DC 	Power suppl Connect the supply voltag (see 'Specifi
power supply, grounding the device	/ More a

wiring

input o its type respective terminals e back.

e transmitters must externallv!

۱g

outputs o their types ications') ective terminals.

ŋg

unit twork line ective terminals.

oly wiring right power ge for your device ications').

More detailed wiring diagrams are available at comecogroup.com under 'Support' tab.



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BDI67U

OPERATION MANUAL



Please read this Operation Manual before mounting and operating!

Save the Manual for future references!

v16-05.12

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Overview	2	Wa	ste Disposal	15
	BDI67U is a low-cost multifunctional programmable process indicator. Its universal input accepts the most common RTDs, thermocouples, and linear signals. The device can be equipped with up to 2 alarm outputs, which can control various actuators using ON/OFF control algorithm, and the optional RS485 interface enables networking. The BDI67U indicator allows adjusting of the built-in digital filters and the programmable output delay, resulting in increased operation reliability in case of industrial interferences.	X	Do not dispose of electronic devices together with household waste material!	If disposed of within European Union, this product should be treated and recycled in accordance with the laws of your jurisdiction implementing the WEEE Directive 2002/96 on the Waste Electrical and Electronic Equipment.
Input Setting				
	 Open the case to reach the configuration jumpers J1 and J2, located on the main board. 			
Input type short out 010 V J2 all the rest J1	 To set the desired input type, short out the respective configuration jumper. 			

Communication Protocol

Notes:

- BDI67U adds 3 spaces in the beginning of the response.
- BDI67U returns decimal point even when the value is integer.
- #13 (CR) is byte 0x0D;
 #10 (LF) is byte 0x0A.
- The U255 command should be used only in case just one slave is presented.

Protocol examples:

PC or other device: BDI67U response:

activating device numb U10#13#10		13#10
reading filter time f.t#13#10	f.t	0015.#13#10
writing filter time of 30 f.t 30#13#10	f.t	0030.#13#10

reading input value of	27.5	
p.v#13#10	p.v	027.5#13#10

invalid command.	command not recognized
parity error.	parity error detected
not a number.	attempt to write symbols for numerical parameter
point error.	value resolution greater than parameter's one
out of range.	value out of range
unit is busy.	writing is allowed only to device at Basic level
read only.	parameter is read-only
can't save.	problem with writing in non-volatile memory

 The device remains active until it receives another Ux command, but with different device address, a F A, L error, or with reset.

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 Any Baud Rate value change through the communication interface also deactivates the device.

Reading from a device

- If the frame consists of only one word, it is recognized as a command for reading.
- The device responds to it by returning the same word and its value, according to Table 2.

Writing in a device

- If the frame consists of two words, it is recognized as a command for writing.
- With writing, transferred are the same two words that would have been received at the respective command for reading from the device.
- After successful writing, the device responds with the respective command for reading, except for the baud command.

Other device responses

- When Error Info value is -1, the device substitutes any command for error reading.
- BDI67U responses in case of incorrect protocol use are given on the left.

Reset

To reset the device, send command reset.

Place BDI67U into a 136x66 mm panel cut-out. Tighten it into place using the enclosed mounting brackets.

Electro-Magnetic Interference (EMI) Issues

Mounting

- All signal wires must be shielded. They must not be packaged together with power cables!
 Never lay the signal wires close to inductive or capacitive noise
- to inductive or capacitive noise sources, such as relays, contactors, motors, etc.!
- All shields have to be grounded ONLY at one end, as closer as possible to the indicator terminals!
- Avoid sharing supply lines with powerful consumers, especially with inductive loads, switched on and off.
- To stop unwelcome interference signals entering through the power supply lines, use shielded 1:1 isolation transformer!
- Shunt all switched (not only those switched by the indicator) inductive consumers with special suppression networks: RC group and varistor for AC loads, or diode - for DC loads.
- If the indicator operates in a very powerful EMI area, it has to be mounted inside a grounded metal shielding box!
- To protect the interface from electromagnetic disturbances, follow the RS485 standard guidelines.

Parameter	Symbol	Description		
Configuratio	on Paramete	ers (These parameters are part of Configuration level)		
Input Type	ı nP	Type of signal that can be connected to the device input		
Unit	טחו ל	Temperature measurement unit		
Point Position	● PnŁ	Display decimal point position		
Input Low	, Lo	Display value at low limit of the linear input range		
Input High	, <u>Н</u> ,	Display value at high limit of the linear input range		
Input Correction	ובר	Constant to be added to the measured input value		
Address	Rddr	Device address		
Baud Rate	ხჩაძ	Serial interface rate		
Gradient	GrØd	Maximum input signal change during the sampling period (120 ms)		
Filter Time	F.Ł	Relative time constant of the input filter		
Filter Band	F.Ь	Zone around the measured value, within which the filter is active		
SP limit Low	SPL	Set-point Low limit		
SP limit High	SPH	Set-point High limit		
Direction 1	di r. l	Control action direction of output REL1		
Direction 2	dı r.2	Control action direction of output REL2		
Parameters	of the cont	rol algorithm (These parameters are part of Parametric level)		
+ Differential 1	P.d. 1	Positive Differential of output REL1		
- Differential 1	n.d. 1	Negative Differential of output K1		
Time On 1	E.n. 1	ON duration of output REL1		
Time Off 1	£.F. 1	OFF duration of output REL1		
Hold 1	HL d. I	Holds the output reaction of output REL1		
		with index 2 - for output REL2		
Parameters	of Basic (o	perating) level		
Set Point 1	5.P. I	Set-point value of output REL1		
Set Point 2	5.P.2	Set-point value of output REL2		

Input Filtration	11
	Peak filter
	 This filter is intended for eliminating pulse spikes (peaks), which can appear in the input signal, in the following way: BDI67U measures the input signal value every 120 ms (sample time). The measured values are compared subsequently. The filter checks the difference between the last two samples. If it does not exceed Gradient value, the device accepts the signal as <i>normal</i>. If the last measured value differs from the previous one by more than the Gradient value, the filter output is held until the device determines a presence of a <i>normal</i> signal. It is possible only if the input signal has not been changed with more than the Gradient value for four subsequent samples. If the device has not determined a <i>normal</i> signal for 20 subsequent samples, <i>n</i>_D, <i>S</i> appears on the display (see 'Basic level').
	Low-pass filter
	 This first-order filter acts ONLY within a certain band around filter output value. This has been designed to cut periodic noises outside the communication signal spectrum. Filter operation is defined by two parameters: Filter Time (defines filter time constant) and Filter Band (defines filter active band around filter output value). If the newly measured value differs from the filter output by more than Filter Band, the filter resets
	with a new initial output value (newly measured value).

Townsh Filtwork

Table 1

٠ ٠ dı r.x=hEAE di r.×= cool alarm ON alarm ON P.d.× n d.× ٠ P.d.× nd.× alarm OFF alarm OFF P٧ PV 5.P.X 5.P.X Algorithm output ON OFF Time Alarm output 1 HL.d.× HL.d.× ON -> OFF Time alarm ON En? ŁF.× alarm OFF Time

Output Control

Alarm output operation The alarm outputs operate according to the control algorithm parameters. The outputs deactivate with the value change of one of the following configuration parameters - Point Position, Input Low, Input

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High, and Input Correction
and remain inactive till Basic level is entered.
The outputs deactivate

also when an error has been detected (see '**Error messaging**').

ON/OFF control algorithm

The static characteristic of an alarm relay controlled by an ON/OFF algorithm is shown on the left drawing.

Output hold

For eliminating undesirable switches of the alarm output, additional parameter (Hold) is assigned to hold the output reaction for certain period of time.

Output pulse mode

When a relay is forced to ON by the control algorithm, it can either stay ON or pulse depending on **Time On** and **Time Off** parameter values. Setting any of these parameters to '0' disables the Pulse mode.

Value	Unit	Notes
PE,h or PE,E	-	Pt100: -100850 °C or Pt1000: -100600 °C
PEC. 1 or PEC.2	-	PTC 1k or 2k: -50150 °C
r.0. 1	-	resistive linear: 01 kΩ
£.c - b	-	T/C "B": 2001800 °C
ב-1	-	T/C "J": -201000 °C
ב-2	-	T/C "K": -201300 °C
Łc-r	-	T/C "R": 01700 °C
£.c - 5	-	T/C "S": 01700 °C
£ב-£	-	T/C "T": -40400 °C
U	-	voltage linear: 0100 mV
1.0.20 or 1.4.20	-	current linear: 020 mA or 420 mA
J.O. 10	-	voltage linear: 010 V
סן,סב	-	°C or °F
x1, x0.1, x0.01, x0.001	-	when indicating values with the input-signal measurement unit (ISU)
-1999 9999	ISU	These parameters make sense ONLY in case of a linear input signal!
-1999 9999	ISU	OFFSET
1254	-	
12,24,48,96	bps	1200, 2400, 4800 (factory-set), or 9600 bps
0 9999	ISU	used for input peak filtration; Value '0' cancels the filtration.
0 9999	-	This parameter and the following one define a low-pass input filter.
0 M	ISU	temperature: whole part of $\mathbf{M} \le 100$; linear: \mathbf{M} = 25% of input range
within input range	ISU	These parameters keep the Set-point in safe limits, preserving it from random changes.
cool,hEAL	-	('cooling', 'heating')
	These	parameters are accessible in the presence of the corresponding relay.
0 9999	ISU	lower than (High input range - Set Point 1)!
0 9999	ISU	lower than (Set Point 1- Low input range)!
0 9999	sec.	Value '0' disables Pulse mode.
0 9999	Sec.	
	These	parameters are accessible in the presence of the corresponding relay.
within input range	ISU	

Error Messaging					
EITUI MESSayiliy	L L L O L	. T.			

Message	Parameters	Error type
FR, L	all	Incorrect memory
Ъгピ	-	Service required!
Er.0	GrAd	Out of range
50.r3	F.Ł	Out of range
Er.03	F.b	Out of range
Er.04	5.P.L	Out of range
Er.05	5.P.H	Out of range
Er.06	S.P.L., S.P.H	5.P.L > 5.P.H
Er. 1 1, Er 2 1	£.n. 1, E.n.2	Out of range
Er. 12,Er22	£.F. 1, E.F.2	Out of range
Er. 13, Er 23	HL d. 1, HL d2	Out of range
Er. 14, Er 24	P.d. 1, P.d.2	Out of range
Er. 15, Er.25	n.d. 1, n.d.2	Out of range
Er. 16,Er26	5.P. 1, 5.P.2	Out of range (5.P.L 5.P.H)
Er.17,Er27	5.P.x - n.d. x	Lower than Input Low Range Limit
Er. 18,Er28	5.P. x + P.d. x	Exceeds Input High Range Limit
Er.29	Addr	Out of range

 In some cases, BDI67U finds non-conformities in parameter values that must be corrected before operating at Basic level.

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Changing

with ISU!

E.g.: changing

Point Position value

of all parameters

Point Position value

from (x1) to (x0.1)

a Set-point value

of 100 to 10.0!!!

would change

reflects the real value

- The device indicates such kind of problems by displaying error messages as given on the left.
 If F, I, L appears on the display,
- on the display, try debugging by turning the power off/on.
- If the problem persists, press and hold or send command error 0 via the communication interface to restore the default (factory) settings.

Parameter Programming

Indicator parameters

BDI67U is a programmable device whose service behavior is determined by a set of parameters. All the parameters, along with their names, symbols, and value ranges, are given in Table 1.

Setting numerical parameter value

- Enter parameter value adjustment mode (see 'Program Levels').
- The whole part of the value together with the left zeroes appears on the display, and the rightmost digit blinks. ____
- ♦ To select another digit, press
- The 3 rightmost digits can accept values from [] to [], and the leftmost digit can also accept the values - and -[.
- To increase or decrease the blinking digit value, use respectively or s.
- If the new value has not been confirmed and no key has been pressed for a certain period of time, value adjustment automatically ceases, and the parameter retains its initial value.

Setting symbolic parameter value

- Enter parameter value adjustment mode (see 'Program Levels').
- Read the blinking parameter value.
 To change the value use solution or solution.

To change the value, use () or (), and to confirm, press () + ()

- or 🔶 + 💌.
- If the new value has not been confirmed and no key has been pressed for a certain period of time, value adjustment automatically ceases, and the parameter retains its initial value.

Program Levels Program Levels Basic level Parametric level This level contains the control At Basic level, BDI67U indicates ςp Basic the measured input value (PV) algorithm parameters. If no alarm output level with a resolution, according to is installed, this level does not show up. the Point Position parameter. • Enter from Basic level by pressing 125.0 If the whole part of PV cannot be ٠ and holding • until PRr appears entirely displayed, the unit on the display. Release the key. generates blinking 'overflow' alarm outputs ♦ ¥ If the key is not released on time, messages (aL or - aL depending on PV sign). BDI67U enters Configuration level. Parametric Choose a parameter If PV is out of its operating range level using \land and 😽 (the input range according PAr to Table 1, extended by 5% To enter parameter value 2 on both sides), the device displays adjustment mode, press blinking symbolic messages: (under-range) or (over-range). When PV is out of physical range, ♦♦ If no key has been pressed for a while, the device automatically returns to Basic level, storing all Configuration the unit displays confirmed changes. level Upon entering Basic level, For quick exiting and saving conf BDI67U may display use key combination $| \ll | + | \gg |$ the, n, E message, indicating that some time Configuration level is necessary for filter initialization. This level contains the configuration The no, 5 message may appear ٠ parameters of the device. as a result of the peak filter operation (see '**Input filtration**'). Enter from Basic level by pressing and holding 🔶 until conF To enter parameter value appears on the display. adjustment mode for Set Point 1, To access and adjust press and hold \land until 5,P. { the configuration parameters, appears on the display. follow the algorithm described To view the Set-point value, in 'Parametric level'. release the key. To enter parameter value adjustment mode for Set Point 2, follow the same procedure, but start with the ≥ key.